

Fiber optic current sensor

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DESCRIPTION

Technical field

The present invention relates to a fiber optic
10 current sensor in accordance with the preamble of
patent claim 1.

Prior art

15 A fiber optic current sensor of the generic
type is known from EP-A-0,856,737. It has a magneto-
optically active sensor fiber which is wound in a coil
and encloses a current conductor. The sensor fiber is
connected, at least at one end, via a phase delay
20 element to a further optical fiber, a so-called feed or
return fiber, via which light can be coupled into or
out of the sensor fiber. The sensor fiber is typically
fabricated from quartz glass and has a round core cross
section. Circularly polarized light propagates in the
25 sensor fiber. The feed and return fibers preferably
have an elliptical core cross section and propagate
linearly polarized light. Acting as phase delay element
is a birefringent fiber segment which is arranged
between the sensor fiber and feed fiber. The fiber
30 segment has main optical axes which are aligned at 45°
to the main axes of the feed and return fibers. Its
length is usually selected such that it acts as a $\lambda/4$
phase delay element. It thereby converts linearly
polarized light of the feed and return fibers into
35 circularly polarized light which propagates in the
sensor fiber.

The sensor fiber is operated either as a Sagnac
interferometer or, when one of its ends is silvered, as

a reflection interferometer. In both cases, two circularly polarized optical waves propagate in the sensor fiber. Here, the waves are oppositely directed in the case of the Sagnac interferometer, and run in the same direction in the case of the reflection interferometer. Both waves have the same sense of polarization in the Sagnac interferometer, being either left-circularly or right-circularly polarized. They have an opposite sense of polarization in the reflection interferometer.

If current is flowing through the current conductor, the current generates a magnetic field which leads to a differential phase shift between these two oppositely directed or identically directed optical waves. This effect is termed the magneto-optic or Faraday effect. The phase shift produced is proportional in this case to the current, and amounts in the Sagnac configuration to

$$\Delta\Phi_S = 2 V N I \quad (1)$$

and in the reflection configuration to

$$\Delta\Phi_R = 4 V N I \quad (2),$$

V denoting the Verdet's constant of the fiber, N the number of fiber windings in the coil, and I the current intensity.

The sensor fiber described in EP-A-0,856,737 is certainly free from mechanical stresses, and so the sensor signal obtained is not disturbed by a temperature-dependent, stress-induced linear birefringence. However, the Verdet's constant V likewise exhibits a temperature dependence which is noticeable even in the case of an ideal, stress-free fiber coil. Thus in the case of a quartz fiber the temperature dependence per °C is approximately 0.7×10^{-4} . The sensor signal therefore changes by 0.7% given the temperature fluctuation by 100°C. However, for applications of the current sensor in high-voltage installations there is frequently a need for substantially higher accuracy of current measurement.

Typical values are $\pm 0.2\%$ in the temperature range from -40°C to $+85^{\circ}\text{C}$.

Summary of the invention

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It is therefore the object of the invention to create a fiber optic current sensor of the type mentioned at the beginning which exhibits an improved temperature compensation.

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This object is achieved by a current sensor having the features of patent claim 1.

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According to the invention, the current sensor has at least one phase delay element with a temperature dependence which at least approximately compensates for a temperature dependence of a Verdet's constant of a sensor fiber.

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The compensation comes about by virtue of the fact that the phase delay element has an appropriate phase delay angle which deviates from a phase delay angle of an ideal phase delay element. In this case, it is selected to be larger or smaller as a function of a sign of its temperature dependence than that of the ideal phase delay element, for example as a 90° phase delay angle of an ideal $\lambda/4$ segment.

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Moreover, in the case of a Sagnac interferometer, the phase delay angle is selected as a function of a relative alignment of fast axes of the phase delay element to one another.

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The phase delay element is preferably a birefringent fiber segment with an elliptical core cross section, it being possible to set the phase delay angle by selecting the length of the segment.

Further advantageous embodiments follow from the dependent patent claims.

Brief description of the drawings

The subject matter of the invention is explained in more detail below with the aid of preferred exemplary
5 embodiments which are illustrated in the attached drawings, in which:

figure 1 shows a schematic of a fiber optic current sensor in the form of a Sagnac interferometer;

figure 2 shows a graph of a normalized scale
10 factor as a function of temperature;

figure 3 shows a graph of a normalized scale factor of the sensor in accordance with figure 1, as a function of a deviation δ of a phase delay of a 90° phase delay angle of an ideal $\lambda/4$ segment; and

15 figure 4 shows a schematic of a fiber optic current sensor in a reflection configuration.

Ways of implementing the invention

20 Figure 1 shows a fiber optic current sensor in a Sagnac configuration. Its basic design and its mode of operation are known from the prior art cited at the beginning. It will not be examined in detail below.

A sensor fiber 1 with a round core cross
25 section is wound in a coil about a current conductor S. A first end of the sensor fiber 1 is connected to a feed fiber 2, and a second end is connected to a return fiber 3. Feed and return fibers 2, 3 preferably have an elliptical core cross section. The connection of feed
30 and return fibers 2, 3, respectively, to the sensor fiber 1 is performed via in each case at least one, here exactly one phase delay element 4, 5.

In the example illustrated here, the phase delay elements 4, 5 are short segments of a
35 birefringent fiber, preferably with an elliptical core. In this case, the fiber has main optical axes of birefringence which coincide with the main axes of the elliptical core. The core therefore has a long and a

short main axis, the short main axis being termed the fast axis.

The feed and return fibers 2, 3 are joined to the phase delay elements 4, 5 such that the short main axes of the fiber cores of the two fibers form a defined deflection angle, preferably of 45° . A linear polarization in the feed fiber, which is aligned parallel either to the long or to the short core axis, is split upon entry into the phase delay element into two orthogonal polarization components which are directed parallel to the main axes of the core of the phase delay element. The two polarization components propagate at different speeds because of the birefringence, the rate of propagation of the component parallel to the fast axis being higher than the other. At the end of the phase delay element, the two polarization components have accumulated a differential phase delay which may be described by a phase delay angle ϕ . The phase delay angle ϕ increases in proportion to the length of the phase delay element. In the case of an ideal $\lambda/4$ segment of zeroth order, the differential delay corresponds to a quarter of the wavelength, and the phase delay angle ϕ is 90° . The light emerging from the phase delay element is then circularly polarized. In the case of a $\lambda/4$ segment of higher order, the phase delay angle corresponds to an odd multiple of 90° .

The feed and return fibers 2, 3 are connected to a gyroscopic module 6, which is likewise known. The gyroscopic module 6 has a light source, in particular a laser diode 60, two fiber couplers 61, 62, a fiber polarizer 63, a phase modulator 64, a photodiode 65 and a signal processor 66. An optical wave generated in the laser diode 60 passes via the first fiber coupler 61 into the fiber polarizer 63, is linearly polarized and subsequently decomposed into two component waves in the second fiber coupler 62. The first component wave, which continues to be linearly polarized, passes via

the feed fiber 2 to the first phase delay element 4, is converted into circularly polarized light and launched into the sensor fiber 1. Subsequently, it passes via the second phase delay element 5, where it is
5 reconverted into linearly polarized light, and further via the return fiber 3 and the phase modulator 64 back to the second phase coupler 62. The second component wave traverses the interferometer in the opposite direction. The direction of propagation and
10 polarizations of the two component waves are represented in figure 1 with arrows.

Thus, two oppositely directed optical waves propagate in the sensor fiber 1. If current is flowing through the current conductor L, these two waves
15 experience the differential phase shift $\Delta\Phi_s$ proportional to the current which was mentioned at the beginning.

According to the invention, the temperature dependence of phase delay in the phase delay elements
20 4, 5 is now utilized in order to compensate for the temperature dependence of the Verdet's constant V at least approximately. Such a compensation is illustrated in figure 2, a sensitivity of the sensor, called the normalized scale factor SK, being represented as a
25 function of temperature. A virtually temperature-independent scale factor was achieved by selecting a suitable phase delay angle, something which is represented in the function K(T). The function K(T) is the product of the functions TW(T) and TV(T). In this
30 case, TV(T) shows how the scale factor SK changes on the basis of the temperature dependence of the Verdet's constant. TW(T) describes the change in the scale factor SK owing to the temperature-dependent phase delay in the phase delay elements 4, 5. Consequently,
35 according to the invention the temperature dependence of TW(T) is selected such that it at least approximately compensates for that of TV(T). In this

case, the normalized scale factor SK is increased or reduced as a side effect.

In a fiber optic phase delay element, the desired phase delay angle can be achieved by selecting the length L of the fiber segment. An ideal $\lambda/4$ segment of zeroth order has a phase delay angle of 90° , the ideal length of the segment being for this a quarter of a beat length of orthogonal polarization modes. In a λ/n segment of order -m, the ideal length is an m-multiple of $1/n$. In the case of a phase delay element temperature-compensated according to the invention, the length L thereof deviates from this ideal length. Which phase delay angle or which length L are, however, suitable for temperature compensation is revealed from the following considerations:

The propagation of the optical waves through the various fiber optic paths of the current sensor can be described by means of the Jones matrices. If the phase delay in the two $\lambda/4$ phase delay elements is exactly 90° , that is to say if the two oppositely directed waves are exactly circularly polarized, the current-induced differential phase shift between the two waves is given by equation (1) in the case of an ideal, temperature-independent fiber coil. If the phase delay in the two phase delay elements deviates from this ideal of phase delay angle of 90° , the current-induced phase shift is

$$\Delta\Phi'_s = 2 \arctan [\tan (\Delta\Phi_s/2) \cos(\delta_1/2 + \delta_2/2) / \cos (\delta_1/2 - \delta_2/2)] \quad (3)$$

$\Delta\Phi_s$ is given in this case by equation (1). δ_1 and δ_2 relate to the deviation of the differential phase delays φ_1 and φ_2 in the two phase delay elements.

$$\delta_1 = \varphi_1 - 90^\circ \quad (4)$$

$$\delta_2 = \varphi_2 - 90^\circ \quad (5).$$

Equation (3) holds for the case in which the two phase delay elements 4, 5 each have a fast axis which are orientated at 90° to one another.

For sufficiently small values of $\Delta\Phi$, δ_1 and δ_2 , equation (3) can be written to a good approximation as

$$\Delta\Phi'_s \approx \Delta\Phi_s [1 - (1/2)\delta_1\delta_2] \quad (6)$$

If the fast axes of the two phase delay elements 4,5 are aligned parallel to one another, equation (6) is replaced by

$$\Delta\Phi'_s \approx \Delta\Phi_s [1 + (1/2)\delta_1\delta_2] \quad (7)$$

If the fast axes are at an angle of 45° to one another, it follows that

$$\Delta\Phi'_s \approx \Delta\Phi_s [1 - (1/2)(\delta_1\delta_2/2)^2] \quad (7)$$

The sensitivity of the current sensor, that is to say its normalized scale factor SK, is described in this case by the ratio $\Delta\Phi'_s/\Delta\Phi_s$.

In figure 3, the scale factor SK from the three abovenamed different alignments of the fast axes is represented as a function of δ . In this case, δ is a deviation of the phase delay angle φ from the phase delay angle of an ideal $\lambda/4$ segment, that is to say from 90° here. In the example illustrated here, the first and second phase delay elements 3, 4 have the same deviation $\delta = \delta_1 = \delta_2$. The curve denoted by A represents the scale factor for fast axes, which are aligned parallel to one another, for the two phase delay elements 3, 4. The curve denoted by B shows the scale factor of a current sensor with two phase delay elements, whose fast axes form an angle of 45° , and in the case of curve C the first axes are aligned orthogonal to one another. Curve B shows a dependence of δ to the fourth power, whereas curves A and C represent quadratic dependences.

In accordance with figure 3, the contribution of the $\lambda/4$ segments to the temperature dependence of the scale factor is larger the more the phase delay deviates from 90° . For $\lambda/4$ segments of higher order, the temperature dependence increase in proportion to the order in this case. By appropriately selecting the phase delay angle when producing the phase delay elements 4, 5, it is possible to selectively influence

their contribution to the temperature dependence of the scale factor SK.

The type of phase delay element is to be taken into account in this case. If optical fibers are used, their temperature dependence depends strongly on the type of fiber. Fibers with stress-induced birefringence, such as a panda fiber or a bow tie fiber, have a markedly higher temperature dependence than fibers with an elliptical core cross section, whose birefringence is determined by geometry. In addition, the phase delay angle is selected as a function of the sign of the temperature dependence.

In the example illustrated here, the aim is to achieve a temperature compensation in the range of -40°C to $+80^{\circ}\text{C}$. As already mentioned, the contribution of the Verdet's constant V to the temperature dependence of the current sensor is $0.7 \times 10^{-4}/^{\circ}\text{C}$, that is to say between -40°C and $+80^{\circ}\text{C}$ the sensor signal increases by 0.84% because of this contribution, given a constant current. The contribution of the two phase delay elements 3, 4 should therefore lower the signal by 0.84% over this temperature range. In this case, the type of phase delay elements and the mutual alignment of their fast axes are to be taken into account.

1st example:

In a first example of a current sensor in accordance with figure 1, the temperature dependence of the phase delay is $-0.0153^{\circ}/^{\circ}\text{C}$, as is typical for a $\lambda/4$ segment made from a commercial quartz glass fiber with an elliptical core. Furthermore, the fast axes of the $\lambda/4$ segments are orientated at least approximately in parallel. An optimum temperature compensation of the sensor is achieved when the phase delay angle of the $\lambda/4$ segments is set in the case of room temperature (20°C) to at least approximately 150° instead of 90° , as is illustrated in figure 2. In the case of a wavelength of 820 nm, the length of the fiber optic

phase delay segment is therefore 1.11 mm. An ideal $\lambda/4$ segment would have a length of 0.95 mm. The normalized scale factor SK increases from 1 to 1.035.

5 2nd example:

In a second example, the first axes of the $\lambda/4$ segments are orientated not in parallel, but at least approximately orthogonally. An optimum temperature compensation is reached whenever the phase delay angle
10 is set to at least approximately 75° . The length of the fiber optic phase delay segment is 0.79 mm. The normalized scale factor SK decreases to 0.965.

In the case of non-parallel or orthogonal axes of the $\lambda/4$ segments, temperature compensation is
15 likewise possible when the relative axial alignment is known. The relationship between $\Delta\Phi'_s$ and δ must be correspondingly calculated for this purpose with the aid of the formalism of the Jones matrices. However, with increasing deviation from the orthogonal or
20 parallel axial orientation, it is necessary, as is clear from figure 2, to select a larger deviation in the phase delay of 90° by comparison with a configuration with orthogonal or parallel axes, in order to achieve as complete a temperature compensation
25 as possible.

If use is made of phase delay elements with a greater temperature dependence (for example fiber segments with stress-induced birefringence, a correspondingly smaller deviation in the phase delays
30 of 90° is to be selected for the temperature compensation.

It is also possible in principle to use two $\lambda/4$ segments with different phase delays and temperature dependences as long their combined action compensates
35 for the temperature dependence of the Verdet's constant.

Furthermore, it is also possible to use $\lambda/4$ plates as phase delay elements instead of the

abovedescribed $\lambda/4$ segments, the temperature compensation being performed by selecting the appropriate thickness of the plates.

INS. B' > 5 ~~A fiber optic current sensor with a reflection~~
interferometer is illustrated in figure 4. By contrast
with the abovedescribed Sagnac interferometer, this
current sensor has no return fiber, but an end of a
sensor fiber 1 averted from the feed fiber 3 is
designed as reflector 3'. As regards the temperature
10 compensation, this configuration forms a special case
of the current sensor in accordance with figure 1.
Given a deviation δ in the phase delay ϕ of the $\lambda/4$
segment of 90° , the reflection interferometer behaves
like a Sagnac interferometer with two identical $\lambda/4$
15 segments whose axes are aligned orthogonally. The
current-induced differential phase shift is then
approximately

$$\Delta\Phi'_R \approx \Delta\Phi_R [1 - \delta^2/2] \quad (9).$$

$\Delta\Phi_R$ is given by equation (2). If the
20 temperature dependence of the phase delay of the $\lambda/4$
segment is $-0.0153^\circ/^\circ\text{C}$, as in the above example, the
phase delay angle is to be set to 75° at room
temperature, and the length L of the segment is to be
selected correspondingly in order to achieve
25 compensation of the temperature dependence of the
~~Verdet's constant V .~~

The reflection interferometer has the advantage
that in conjunction with a known temperature dependence
of the $\lambda/4$ segment only the phase delay (that is to say
30 the length of the segment) need be selected correctly
for a given temperature (in general room temperature)
in order to achieve temperature compensation.

List of reference symbols

S	Current conductor
L	Length of the phase delay element
A	Parallel fast axes
B	Fast axes at 45°
C	Orthogonal fast axes
TW	Temperature dependence of the phase angle
TV	Temperature dependence of the Verdet's constant
K	Temperature-compensated current sensor
φ	Phase delay angle
1	Sensor fiber
2	Feed fiber
3	Return fiber
3'	Reflector
4	First phase delay element
5	Second phase delay element
6	Evaluation module
60	Laser diode
61	First fiber coupler
62	Second fiber coupler
63	Fiber polarizer
64	Phase modulator
65	Photodiode
66	Signal processor